

Power Transducer Series

MULTI POWER TRANSDUCER MODEL **LSMT3**

MODEL & SUFFIX CODE SELECTION

LSMT3-AD2

MODEL _____

AUXILIARY POWER SUPPLY _____

AD2 : 85 – 253V AC / 85 – 253V DC (universal)

ORDERING INFORMATION

Specify code number. (e.g. LSMT3-AD2)
 Use Ordering Information Sheet. (No. ESU-1955)

GENERAL SPECIFICATIONS

Construction: Stand-alone; terminal access at the front
Enclosure protection

Terminal block: IP20

Housing: IP40

Connection: Connector type screw terminal block
 (max. applicable single-core wire size 4.0 mm² or multi-strand wire size 2 × 2.5 mm²)

Configuration: Single phase, 3-phase/3-wire balanced/unbalanced load, 3-phase/4-wire balanced/unbalanced load

Housing material: Flame-resistant resin (grey)

Isolation: Three way (input to each output to power)

Output: Analog output, 3 points

Measured variables

Voltage: U, U12, U23, U31, U1N, U2N, U3N

Current: I, I1, I2, I3, IM, IMS, IB, BS

Active power: P, P1, P2, P3

Reactive power: Q, Q1, Q2, Q3

Apparent power: S, S1, S2, S3

Power factor: PF, PF1, PF2, PF3, QF, QF1, QF2, QF3, LF1, LF2, LF3

Frequency: F

Refer to 'Symbols' for the meaning of each symbol.

CE

mm (inch)

Functions & Features

- Measures simultaneously several variables of a heavy-current power system: current, voltage, active power, reactive power, apparent power and power factor
- Programmable 3 analog outputs
- Input voltage up to 693V (phase-to-phase)
- High accuracy: Class 0.5
- AC/DC universal power supply of wide range
- Bent output characteristic selectable
- DIN rail mounting
- Conforms to IEC 688

Typical Applications

- Supervises variables of an electrical power system at the incoming panel

INPUT

Rated frequency: 50 / 60 Hz

Rated voltage

Phase-to-phase: 100 to 693V

Phase-to-neutral: 57.7 to 400V

Rated current: 1 to 6A

Waveform: Sinusoidal

Programmable input range: See Table 1.

Consumption VA

Current circuit: $\leq I^2 \cdot 0.01\Omega$ / phase

Voltage circuit: $\leq U^2 / 400k\Omega$ / phase

Thermal rating

| CURRENT INPUT | NUMBER OF INPUTS | OVERLOAD DURATION | INTERVALS |
|-------------------------|------------------|-------------------|-----------|
| 12A | ---- | Continuous | ---- |
| 120A | 10 | 1 sec. | 100 sec. |
| 120A | 5 | 3 sec. | 5 min. |
| VOLTAGE INPUT (1ph/3ph) | NUMBER OF INPUTS | OVERLOAD DURATION | INTERVALS |
| 480 / 831V | ---- | Continuous | ---- |
| 600 / 1040V | 10 | 10 sec. | 10 sec. |
| 800 / 1386V | 10 | 1 sec. | 10 sec. |

Table 1. Programmable Input Range

| | X0 (0% input) | X2 (100% input) |
|---------------------|--|--|
| P, Q (System) | $-X2 \leq X0 \leq 0.8 X2$ | $0.3 \leq X2 / Sr \leq 1.5$ |
| P, Q (L1 / L2 / L3) | $-X2 \leq X0 \leq 0.8 X2$ | $0.1 \leq X2 / Sr \leq 0.5$ |
| S (System) | $0 \leq X0 \leq 0.8 X2$ | $0.3 \leq X2 / Sr \leq 1.5$ |
| S (L1 / L2 / L3) | $0 \leq X0 \leq 0.8 X2$ | $0.1 \leq X2 / Sr \leq 0.5$ |
| PF, QF, LF | $-1 \leq X0 \leq (X2 - 0.5)$ | $0 \leq X2 \leq 1$ |
| F | $45 \text{ Hz} \leq X0 \leq (X2 - 1) \text{ Hz}$ | $(X0 + 1) \text{ Hz} \leq X2 \leq 65 \text{ Hz}$ |
| I, I1, I2, I3 | $0 \leq X0 \leq 0.8 X2$ | $0.5 Ir \leq X2 \leq 1.2 Ir$ |
| IB, BS | $X0 = 0$ | $0.5 Ir \leq X2 \leq 1.2 Ir$ |
| IM | $0 \leq X0 \leq 0.8 X2$ | $0.5 Ir \leq X2 \leq 1.2 Ir$ |
| IMS | $-X2 \leq X0 \leq 0.8 X2$ | $0.5 Ir \leq X2 \leq 1.2 Ir$ |
| U | $0 \leq X0 \leq 0.9 X2$ | $0.8 Ur \leq X2 \leq 1.2 Ur$ |
| U12 | $0 \leq X0 \leq 0.9 X2$ | $0.8 Ur \leq X2 \leq 1.2 Ur$ |
| U23 | $0 \leq X0 \leq 0.9 X2$ | $0.8 Ur \leq X2 \leq 1.2 Ur$ |
| U31 | $0 \leq X0 \leq 0.9 X2$ | $0.8 Ur \leq X2 \leq 1.2 Ur$ |
| U1N | $0 \leq X0 \leq 0.9 X2$ | $0.8 Ur / \sqrt{3} \leq X2 \leq 1.2 Ur / \sqrt{3}$ |
| U2N | $0 \leq X0 \leq 0.9 X2$ | $0.8 Ur / \sqrt{3} \leq X2 \leq 1.2 Ur / \sqrt{3}$ |
| U3N | $0 \leq X0 \leq 0.9 X2$ | $0.8 Ur / \sqrt{3} \leq X2 \leq 1.2 Ur / \sqrt{3}$ |

OUTPUT

DC CURRENT

Programmable range

Y2 (100% output): 1 to 20mA

Y0 (0% output): -Y2 to 0.2 Y2

Output limits for input overload:

[Y0 - 0.2 Y2] to Y0 for lower limit

Y2 to 1.2 Y2 for upper limit

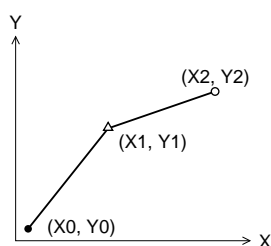
Load resistance: 7.5 / Y2 Ω (max. output drive 7.5V)

BENT CHARACTERISTIC: 1 break point

Programmable range

X1 (input break point): [X0 + 0.015 X2] thr. 0.985 X2

Y1 (output break point): Y0 thr. Y2



INSTALLATION

Power input

AC: Operational voltage range 85 – 253V, 50/60 Hz, ≤ 7VA

DC: Operational voltage range 85 – 253V, ripple 10% p-p max., ≤ 5W (approx.)

Operating temperature: -10 to +55°C (14 to 131°F)

Storage temperature: -25 to +55°C (-13 to +131°F)

Operating humidity: 90% RH max. (non-condensing)

Vibration: 2G

Mounting: DIN rail

Dimensions: W105×H69.1×D112.5 mm
(4.13"×2.72"×4.43")

Weight: 350 g (0.77 lbs)

PERFORMANCE

Reference conditions for accuracy

Ambient temperature: 15 to 30°C

Pre-conditioning: 30 minutes

Power supply: Rating ±1%

Active/reactive factor: $\cos\phi = 1 / \sin\phi = 1$

Waveform factor: 1.1107

Output load: DC current output, 7.5 / Y2 ±1% (Ω)

Ripple: ≤ ±2% of Y2

Dielectric strength: 3700V AC @1 minute

(voltage input or current input to power or output or housing)

2200V AC @1 minute (between each voltage input, each current input)

3700V AC @1 minute

(power to output or housing)

3700V AC @1 minute (current input to power or output or housing)

490V AC @1 minute

(between each output)

490V AC @1 minute (output to housing)

Accuracy class at 100% output

| MEASURED VARIABLE | CONDITION | ACCURACY CLASS (%) |
|--|--|--------------------|
| System: Active, reactive and apparent power | $0.5 \leq X2/Sr \leq 1.5$ $0.3 \leq X2/Sr < 0.5$ | 0.5 c 1.0 c |
| Phase: Active, reactive and apparent power | $0.167 \leq X2/Sr \leq 0.5$ $0.1 \leq X2/Sr < 0.167$ | 0.5 c 1.0 c |
| Power factor | $0.5 Sr \leq S \leq 1.5 Sr$, $(X2 - X0) = 2$ | 0.5 c |
| | $0.5 Sr \leq S \leq 1.5 Sr$, $1 \leq (X2 - X0) < 2$ | 1.0 c |
| | $0.5 Sr \leq S \leq 1.5 Sr$, $0.5 \leq (X2 - X0) < 1$ | 2.0 c |
| | $0.1 Sr \leq S < 0.5 Sr$, $(X2 - X0) = 2$ | 1.0 c |
| | $0.1 Sr \leq S < 0.5 Sr$, $1 \leq (X2 - X0) < 2$ | 2.0 c |
| | $0.1 Sr \leq S < 0.5 Sr$, $0.5 \leq (X2 - X0) < 1$ | 4.0 c |
| AC voltage | $0.1 Ur \leq U \leq 1.2 Ur$ | 0.5 c |
| AC current | $0.1 Ir \leq I \leq 1.2 Ir$ | 0.5 c |
| Frequency | $0.1 Ur \leq U \leq 1.2 Ur$ $0.1 Ir \leq I \leq 1.2 Ir$ | $0.15 + 0.03 c$ |

Factor 'c' (the highest value applies)

- Linear characteristic

$$c = \frac{1 - \frac{Y0}{Y2}}{1 - \frac{X0}{X2}} \text{ or } c = 1$$

- Bent characteristic

$$c = \frac{Y1 - Y0}{X1 - X0} \cdot \frac{X2}{Y2} \text{ or } c = 1$$

$$c = \frac{1 - \frac{Y1}{Y2}}{1 - \frac{X1}{X2}} \text{ or } c = 1$$

STANDARDS & APPROVALS

CE conformity: EMC Directive (89/336/EEC)

EMI EN61326-1

EMS EN61326 / A1

Low Voltage Directive (73/23/EEC)

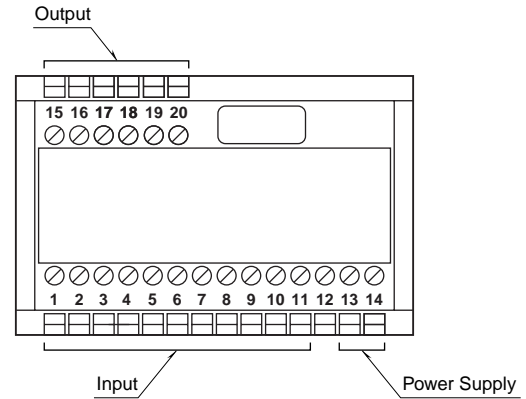
EN61010

Class II, Installation category II (at 300V)

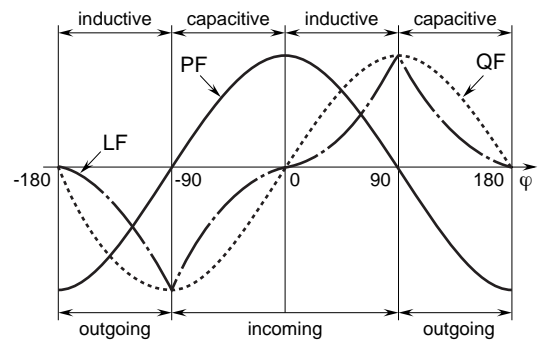
/ III (at 600V), Pollution degree 2

IEC Standard: IEC 688 usage group II

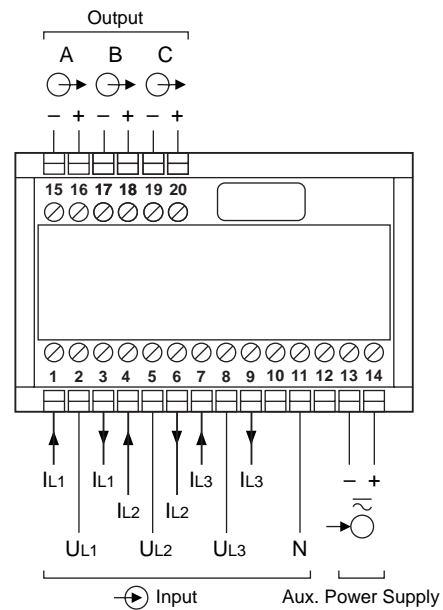
FRONT PANEL CONFIGURATION



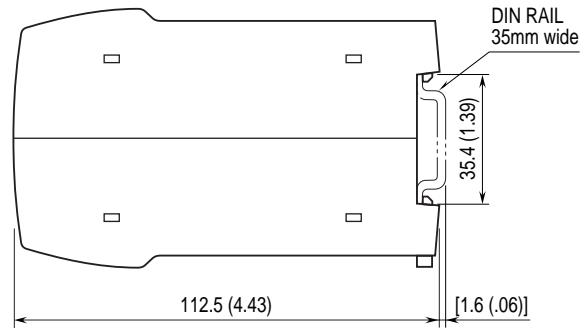
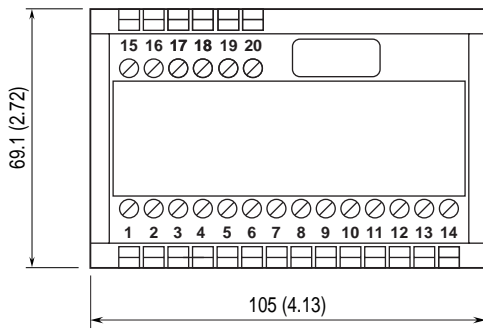
POWER FACTOR RELATIONSHIP



CONNECTION DIAGRAM



EXTERNAL DIMENSIONS & TERMINAL ASSIGNMENTS mm (inch)



•When mounting, no extra space is needed between units.

SYMBOLS

| | | | |
|-----------|---|-----|--|
| X0 | 0% input | F | Frequency |
| X1 | Input break point | P | Active power of the system |
| X2 | 100% input | P1 | Active power, phase 1, L1 – N |
| Y0 | 0% output | P2 | Active power, phase 2, L2 – N |
| Y1 | Output break point | P3 | Active power, phase 3, L3 – N |
| Y2 | 100% output | Q | Reactive power of the system |
| Y2SW | 100% output setpoint | Q1 | Reactive power, phase 1, L1 – N |
| U | Input voltage | Q2 | Reactive power, phase 2, L2 – N |
| Ur | Rated input voltage | Q3 | Reactive power, phase 3, L3 – N |
| U12 | Phase-to-phase voltage, L1 – L2 | S | Apparent power of the system |
| U23 | Phase-to-phase voltage, L2 – L3 | S1 | Apparent power, phase 1, L1 – N |
| U31 | Phase-to-phase voltage, L3 – L1 | S2 | Apparent power, phase 2, L2 – N |
| U1N | Phase-to-neutral voltage, L1 – N | S3 | Apparent power, phase 3, L3 – N |
| U2N | Phase-to-neutral voltage, L2 – N | Sr | Rated apparent power |
| U3N | Phase-to-neutral voltage, L3 – N | PF | Active power factor $\cos\varphi = P / S$ |
| I | Input current | PF1 | Active power factor 1, $P1 / S1$ |
| Ir | Rated input current | PF2 | Active power factor 2, $P2 / S2$ |
| I1 | AC current L1 | PF3 | Active power factor 3, $P3 / S3$ |
| I2 | AC current L2 | QF | Reactive power factor $\sin\varphi = Q / S$ |
| I3 | AC current L3 | QF1 | Reactive power factor 1, $Q1 / S1$ |
| IM | Average current $(I1 + I2 + I3) / 3$ | QF2 | Reactive power factor 2, $Q2 / S2$ |
| IMS | Average value of the currents and sign of the active power (P) | QF3 | Reactive power factor 3, $Q3 / S3$ |
| IB | RMS value of the current with wire setting range (bimetal measuring function) | LF | Power factor of the system, $\text{sgn}Q (1 - PF)$ |
| BS | Slave pointer function for the measurement of the RMS value IB | LF1 | Power factor phase 1, $\text{sgn}Q1 (1 - PF1)$ |
| φ | Phase-shift between current and voltage | LF2 | Power factor phase 2, $\text{sgn}Q2 (1 - PF2)$ |
| | | LF3 | Power factor phase 3, $\text{sgn}Q3 (1 - PF3)$ |
| | | c | Intrinsic error factor |